Remote-2

Remote control of ZENNIUM series potentiostats



2024-04-25



| 1 Introduction | 1 |
|--|----------------------------|
| 2 Thales Remote | 1 2 3 4 5 6 |
| 3 Communication Functions of Remote Control | 8 |
| 4 Instruction Set of Remote Control. 4.1 Format of command strings 4.2 Potentiostat setup – commands 4.2.1 Changing devices | 8 8 9 9 |
| 4.2.2 Operating mode | 9 |
| 4.2.3 Potentiostat turn on/off | 9 |
| 4.2.4 Setpoint values | 10 |
| 4.3 Measure single values | 10 11 |
| 4.4 Rule file 4.5 Without Rule file 4.5.1 Electrochemical impedance spectroscopy (EIS) | 11 12 12 |
| 4.5.2 Current-voltage curve (IE) | 14 |
| 4.5.3 Cyclic voltammetry (CV) | 17 |
| 4.5.4 Remote Sequencer | 19 |
| 4.5.4.1 Set Sequencer Parameters | 19 |
| 4.6 File handling | 21 |

ZAHNER

| 4.7 Export ASCII Data Settings | 22 |
|--|----|
| 4.8 Remote – FRA-Mode | 23 |
| 4.9 Data acquisition / Virtual instruments | 25 |
| 4.10 MIO card | |
| 4.11 Acquire system parameters | |
| 4.12 Additional commands | 27 |
| 4.12.1 PAD4 setup | 27 |
| 4.12.2 Potential range | 28 |
| 4.12.3 Shunt range | |
| 4.12.4 Clear memory | 28 |
| 5 Commands | |
| 5.1 New commands | |
| 6 Errors - Table | |
| | |



1 Introduction

The *ZENNIUM* series potentiostats are controlled by the Thales software package providing a graphical user interface for measuring and analyzing electrochemical data. In addition, the *ZENNIUM* systems can be controlled by external software using a software interface to Thales. As this interface is based on the TCP/IP protocol it is not limited to the local Thales-PC but is also possible remotely over the network.

A dynamic link library (DLL) file is used to interface between external software (e.g. LabVIEW) and the Thales interface (Thales Remote Server). A SCRIPT application running on the *ZENNIUM* will call the specific procedures for each of the commands and parameters.

In our GitHub repository, we offer libraries for controlling the *ZENNIUM* series potentiostats via remote script. The programming languages Python and C++ are supported.



2 Thales Remote

To enable the Thales Remote server, a special application has to be started. This can be done either by:

- 1. Starting the runtime file
- 2. Linking a Thales Script source
- 3. Sending a command from the client

Select one of the described methods to start the remote operation. In chapters 2.1, 2.2, and 2.3 the above-mentioned methods are explained in detail.

The GitHub libraries use option 3 and automatically start the Thales Remote server.



2.1 Running the supplied runtime file

In case no modifications of the remote application are necessary, starting the runtime file is the most convenient way.



Start the Thales software and click on the red Z-icon to open the pull-down menu.

In the pull-down menu choose *Optional Methods* and then click on *Remote Control*.

The remote application starts automatically and awaits a client connection.

At this stage, the communication indicator reads **stopped** because the communication is not set up so far. It will start as soon as a controller software is started.

IMPORTANT: This screen has to be active during the whole remote session. Quitting this screen will stop the remote session.

Alternatively, the runtime file can be loaded with the **EXE**-icon of the Thales main screen. Navigate to **c:\thales\examples\applications** and select remote.rtm.



2.2 Linking the script source



In case modifications of the remote application are desired, the script source is provided for editing.

Start the Thales software and activate the **Script**.



Click the "edit script" button to open the Zahner editor ZEDIT.

| C ZEDIT USB | | <u>a _ o ×</u> |
|------------------------------------|--------|----------------|
| File Edit Font+Colour Options Info | | |
| | | • |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| | | |
| Changed | Insert | Unbekannt |

In ZEDIT, click the import button. In the folder c:\thales\script\remote2\source, load the remote2.is_ file and click "LOAD". The source code can now be edited, if necessary.





In the Thales window, click on the "link script". After linking, the script starts automatically.



At this stage, the communication indicator reads **stopped** because the communication is not set up so far. It will start as soon as a controller software is started.

IMPORTANT: This screen has to be active during the whole remote session. Quitting this screen will stop the remote session.

2.3 Automated start of Remote

When using the *ZENNIUM* remotely, the user can start the remote server without user-interaction, provided that the Thales software is running.

For a more comprehensive explanation of this feature, please refer to the <u>Devcli.dll</u> <u>Programmer's Reference manual</u>, paragraph 5. "Synchronization", function "DevRestartViaPD".



2.4 Thales Remote – SET UP

In the Thales Remote \rightarrow SET UP, the file path, file name, and saving format for different electrochemical measurement techniques can be defined.



In the global settings shown in the image above, one can set:

Path = the folder path, where the measured file will be saved.

Root = (base) file name.

Mode = saving mode for the measured files. A file can be saved using

- date and time mode
- counter mode
- individual mode.

Count = Count number (four digits) for the counter mode

Note: This means that a maximum of 9999 measurements of this type can be saved in a remote session.

All the above-provided parameters can also be remotely defined. For these, the user requires the relevant tokens (see section 5.6).

| Allowed characters for file names and directories: | | |
|--|-------------------------------------|--|
| Alphanumeric characters: | a-z, A-Z, ä, ö, ü, Ä, Ö, Ü, ß, 0-9 | |
| Special characters: | + , - , _ , and the space character | |



2.4.1 Rule file

In remote control, the client has to define every parameter required for the electrochemical measurement using the tokens described below. Alternatively, the client can also use rule files containing predefined parameter sets. In the folder $c:\thales\script\remote2\rules$, rule files for EIS, CV, and IE are present with the names $eis_rule.ism$, $cv_rule.isc$ and $ie_rule.iss$, respectively. These files can be changed to the desired parameters. For using the rule file, the user must define "Use Rulefile = ON" in Thales Remote.

For each measurement method, only one rule file can be saved. The rule file names must be the same as that of the demo rule files. The process of making a rule file is explained in the <u>SCRIPT- an introduction</u> manual.

2.4.2 Global Acknowledge

In former versions of the Thales Remote, not all of the commands returned an "acknowledge-string". This restriction is now eliminated, leading to a more robust handshake.

In the Thales Remote-2 software only the **Global Acknowledge = 2** mode is used by default. This mode cannot be changed as in previous Remote-2 versions.

The global acknowledge extended useful information about the errors is also provided besides the status of the measurement. This will facilitate the users to swiftly prepare error-free remote test routines. When the commands are correct and error-free then an "OK" will be shown in the acknowledge string. In the case of an error in the commands, wrong parameters, or a typo, an ERROR will be shown. The error message will follow the format \rightarrow ERROR;error-type;status (i.e., ERROR;100;1). A complete table about the error-types is provided in chapter 6. The status will explain the expected problem. A small example of the error messages for different *Pot*= values is provided below.

| Pot = | Message | Status | Meaning |
|-----------|--------------|--------|-----------------|
| Pot = 1 | ERROR;100;1 | 1 | value too large |
| Pot = 0.8 | ERROR;101;2 | 2 | not integer |
| Pot = - 2 | ERROR;100;-1 | -1 | value too small |
| Pot = - 1 | OK | 0 | ok |



If the commands are provided in a sequence then the OK/error message will also be provided in sequence (see below). Different commands, status, and error messages are separated with the colon ":"

Command:

1:Pot=2:Pset=1;Gal=-2:Cset=1:CV_Pupper=5:

Response:

ERROR;100;1:OK:ERROR;100;-1:OK:ERROR;100;1:

The commands used in the remote software will also be logged in the Thales Remote window.



Further information regarding the commands is provided in Chapter 4.



3 Communication Functions of Remote Control

The communication functions are described in the <u>DevCli.dll Programmer's</u> Reference Manual.

4 Instruction Set of Remote Control

4.1 Format of command strings

The communication between the Thales Remote and the remote VI software uses ASCII-strings of the following format

X:Command:

X number of the communication channel from 1 to 9. Until now, Thales Remote does not distinguish among different channels, so channels 2 to 9 should be considered as reserved.

The command has to be delimited by a colon (:). Several commands can be sent in one string. In this case, all commands are separated by colons (:), e.g.

X:Command1:Command2:Command3:

Examples of valid command strings are

1:Pset=1.5: \rightarrow Sets the potential to 1.5 V (unit V)

1:CURRENT:POTENTIAL: \rightarrow Returns the actual current and potential value

In case one command in a string is erroneous, all commands within this string will be discarded.

In a sequential string of commands, no commands after CV, EIS, or IE will be processed. Hence no commands should be provided after these measurements. The user must write different command strings for commands after the above-mentioned measurements. An example is provided below

WRONG → 1:Gal=0:GAL=0:Pset=1:Pot=-1:EIS:CURRENT:POTENTIAL:

CORRECT → 1:Gal=0:GAL=0:Pset=1:Pot=-1:EIS: 1:CURRENT: POTENTIAL:



4.2 Potentiostat setup – commands

4.2.1 Changing devices

The Zahner ZENNIUM series potentiostats can be used with boosters i.e., power potentiostats or electronic loads to achieve a higher potential/current range. These additional devices are connected to the ZENNIUM via the EPC42 cards. Each EPC42 card can be used to connect up to 4 boosters and each ZENNIUM potentiostat can have 4 EPC42 cards. Therefore a maximum of 16 such boosters can be connected with the ZENNIUM series potentiostats.

In remote, DEV%=X is used to choose the main potentiostat or the booster. The main potentiostat (ZENNIUM series) has a DEV% number "0". The boosters connected via the EPC42 cards have the DEV%=1, 2, 3.....16.

If the ZENNIUM series potentiostats have a R-Mux card then the first 16 DEV% positions (1 – 16) are assigned to R-Mux and 17 onwards start the EPC42 connections.

4.2.2 Operating mode

With the commands Gal=X and GAL=X, the potentiostatic/galvanostatic mode of the potentiostat is chosen. Setting the operating mode will disable the amplitude (amplitude value = 0).

| | | GAL = 1 | GAL = 0 | GAL = -1 |
|-----------------|----------|---|----------------|--------------------------|
| | Gal = 0 | - | potentiostatic | pseudo- galvanostatic |
| | Gal = -1 | galvanostatic | _ | - |
| 1:Gal=0:GAL=0: | | → Potentiostatic mode | | |
| 1:Gal=-1:GAI | _=1: | ightarrow Galvanosta | tic mode | |
| 1:Gal=0:GAL=-1: | | \rightarrow Pseudo-galvanostatic mode | | |

! These values cannot be set in FRA-mode (FRA=1) -> <u>Remote - FRA-Mode</u>

4.2.3 Potentiostat turn on/off

With the command *Pot=X*, the potentiostat can be turned on and off.



| Thales Remote-2 | ANNER | |
|---------------------------------|-----------|--|
| ightarrow Turn potentiostat off | 1:Pot=0: | |
| ightarrow Turn potentiostat on | 1:Pot=-1: | |
| | | |

4.2.4 Setpoint values

With the commands provided below different setpoint values can be defined in the Thales software.

| 1:Pset=1: | \rightarrow Set DC potential to 1 V (Unit: V) |
|-------------|--|
| 1:Cset=1: | \rightarrow Set DC current to 1 A (Unit: A) |
| 1:Ampl=5: | → Set AC amplitude to 5 mV in potentiostatic mode or 5 mA in galvanostatic mode |
| 1:Frq=1000: | ightarrow Set frequency to 1000 Hz (Unit: Hz) |

Similarly, a complete list of commands is available in chapter 6 which includes commands for many other setpoint values.

4.3 Measure single values

In the remote VI software, single values (like current, voltage, and impedance, etc.) can be easily read with the commands provided below

- 1:CURRENT: \rightarrow Read actual current value
- 1:POTENTIAL: \rightarrow Read actual potential value
- 1:IMPEDANCE: \rightarrow Read impedance value (real and imaginary impedance)
- 1:PAD4IMP: → Read impedance values (real and imaginary impedance) from main channel and PAD4 channels (when activated)

These parameters will be shown with the format -##.@@@^^^^ (see <u>ANDIbasic</u> manual).

For impedance measurement, amplitude (*Ampl*) and frequency (*Frq*) must be defined beforehand and the cell must be switched ON (*Pot=-1*). Otherwise "*Impedance disabled!*" is returned. The command *CURRENT* should be issued before *IMPEDANCE* is called to automatically set the optimal current range of the potentiostat. Hence, a necessary string for single impedance value measurement should be as given below

1:Frq=1000:Ampl=5:Pot=-1:CURRENT:IMPEDANCE:

 \rightarrow read real and imaginary part of impedance in Ω at frequency (Frq) and amplitude (Ampl)



4.3.1 Fast potential/current measurement – single value

With the commands *POTENTIAL/CURRENT*, the potentiostat measures 5000 times potential/current respectively, and then an average value of these 5000 measurements is shown. The extensive measurement with many averages is done to ensure a good signal to noise ratio. Due to 5000 measurements, the measurement time is in the milliseconds range. A ZENNIUM PRO potentiostat requires 300 ms time for a single current/potential measurement.

To quickly measure the potential or current value, the user can use the commands *POTFAST*, *CURFAST*. Before the measurements, the user must define the averages for the measurement. With the faster measurements, the drawback is a lower signal to noise ratio hence the user must use sufficient averages so that the signal to noise ratio is high. The command strings provided below can be used for such a fast single value measurement.

| 1:AVERAGES=1000: | \rightarrow Average range = 100 to 5000 |
|------------------|---|
| 1:POTFAST: | ightarrow Fast potential measurement using averages |
| 1:CURFAST: | \rightarrow Fast current measurement using averages |

With ZENNIUM PRO, a POTFAST/CURFAST measurement with 500 averages will take around 100 ms.

4.4 Rule file

With *UseRuleFile=1*, the usage of the rule file is activated and all the parameters required for the EIS, CV, and/or IE are taken from the rule file and a measurement is completed.

- 1:UseRuleFile=1:EIS: \rightarrow Measure EIS
- 1:UseRuleFile=1:IE: \rightarrow Measure IE
- 1:UseRuleFile=1:CV: \rightarrow Measure CV

With the above-provided command, EIS measurement will be carried out using the rule file and the data will be exported to a predefined folder. The measured spectrum is saved in both Zahner binary (.ism) and ASCII format (.txt). Refer to chapter 4.7 for ASCII format settings.

The user can save a single rule file for each measurement technique in Thales Remote. The process of saving the rule file is explained in the <u>Script – an introduction</u> manual.



4.5 Without Rule file

The measurement techniques (EIS, CV, and IE) can also be carried out without the usage of the rule files. Without a rule file, every parameter has to be individually defined. To deactivate the use of the rule files, the following command string is used.

1:UseRuleFile=0: \rightarrow Deactivate the use of rule file

4.5.1 Electrochemical impedance spectroscopy (EIS)

In the strings provided below, the use of the rule file is deactivated (*UseRuleFile=0*) and an EIS measurement is setup.

1:UseRuleFile=0:DEV%=0:Gal=0:GAL=0:Pset=0.1:Ampl=10:Pot=-1:

1:ScanStrategy=0:ScanDirection=0:

1:Fmin=1:Fstart=1000:Fmax=100000:

1:dfl=4:dfm=8:Nwl=5:Nws=10:

1:EIS:



Here,

- 1. DEV%=0 \rightarrow Device = 0 (Main potentiostat ZENNIUM series)
- 2. Gal=0,GAL=0 \rightarrow Potentiostatic mode
- 3. Pset=0.1 \rightarrow Set potential = 0 V (DC voltage)
- 4. Ampl=10 \rightarrow AC Amplitude = 10 mV (unit: mV)
- 5. Pot=-1 \rightarrow Potentiostat (-1=turn on, 0= turn off)
- 6. ScanStrategy=0 \rightarrow 0 = single sine, 1 = multi-sine, and 2 = frequency table



Thales Remote-2 7. ScanDirection=0 \rightarrow 0 = scan from Fstart to Fmax and down to Fmin 1 = scan from Fstart to Fmin and up to Fmax 8. Fmin=1 \rightarrow Minimum frequency=1 Hz (lower limit) 9. Fstart=1000 \rightarrow Start frequency=1 kHz (start) 10. Fmax=100000 \rightarrow Maximum frequency=100 kHz (upper limit) 11. Dfl=4 \rightarrow Steps per decade=4 (at lower limit) 12. Dfm=8 \rightarrow Steps per decade=8 (above 66 Hz) 13.Nwl=5 \rightarrow Measure periods=5 (at lower limit) 14. Nws=10 \rightarrow Measure periods=10 (above 66 Hz)

Without a rule file, each parameter is individually adjusted. These above-provided command strings will also make the corresponding changes in the Thales test sampling and EIS windows. With the command *EIS*, an EIS measurement will be carried out and the data will be exported to a predefined folder. The measured spectrum will be saved in both Zahner binary (.ism) and ASCII format (.txt). Refer to chapter 4.7 for ASCII format settings.

In Thales EIS and test sampling window, the corresponding changes for the EIS parameters will only be made when an EIS measurement will be carried out using the command *EIS*. Without this final command string, the changed parameter will not be visible in the Test sampling and EIS window.

The same is valid for the CV and IE measurements.

Amplitude parameter (Ampl=) has to be defined after the operating mode settings (GAL=, Gal=). The amplitude parameter will be set to zero after setting operating mode.

Note: A sprectrum requires at least 5 individual measuring points. Therefore, the frequency range and the step width must be sufficiently defined.



4.5.2 Current-voltage curve (IE)

In the IE measurement, three scan modes can be used. These scan modes are

- Steady-state sampling
- Fixed sampling
- Dynamic scan

In the command strings provided below, each parameter required for IE measurement is assigned a value and then strings relevant to each scan mode are provided. In the end, all the commands are checked and an IE is measured without the use of a rule file.

For Steady-state sampling:

1:IE_EckPot1=0:IE_EckPot2=0.5:IE_EckPot3=-0.5:IE_EckPot4=0:

1:IE_EckPot1rel=1:IE_EckPot2rel=1:IE_EckPot3rel=1:IE_EckPot4rel=1:

1:IE_Resolution=10m:

1:IE_SweepMode=0:

1:IE_Toabs=2n:IE_ToreI=15m:IE_WZmin=10:IE_WZmax=50:

1:IE_Imi=-100m:IE_Ima=100m:CHECKIE:

1:IE:

Replace the coloured command strings with the following command strings for the fixed sampling and dynamic scan.

Fixed sampling:

1:IE_SweepMode=1:

1:IE_WZmax=10:

Dynamic scan:

1:IE_SweepMode=2:

1:IE_Srate=10m:







Here,

- 1. IE_EckPot1=0
- 2. IE_EckPot2=0.5
- 3. IE_EckPot3=-0.5
- \rightarrow 1st edge potential = 0 V
- \rightarrow 2nd edge potential = 0.5 V
- \rightarrow 3rd edge potential = -0.5 V
- 4. IE_EckPot4=0
- \rightarrow 4th edge potential = 0 V



| 5. IE_EckPot1rel=1 | \rightarrow 1 st edge potential relative to OCP (1 = Yes, 0 = No) |
|---|--|
| IE_EckPot2rel=1 | \rightarrow 2 nd edge potential relative to OCP (1 = Yes, 0 = No) |
| IE_EckPot3rel=1 | \rightarrow 3 rd edge potential relative to OCP (1 = Yes, 0 = No) |
| IE_EckPot4rel=1 | \rightarrow 4 th edge potential relative to OCP (1 = Yes, 0 = No) |
| 6. IE_Resolution=10m | → Resolution = 10mV (Unit: V) |
| IE_SweepMode=0 dynamic scan | \rightarrow Scan mode: 0 = steady state, 1 = fixed sampling, 2 = |
| 8. IE_Toabs=2n | \rightarrow Absolute current tolerance (Unit: A) |
| 9. IE_Torel=15m | \rightarrow Relative current tolerance (%) |
| 10. IE_WZmin=10 | \rightarrow Minimum wait time = 10 s (Unit: second) WZ=Wartezeit |
| 11. IE_WZmax=50 | \rightarrow Maximum wait time = 50 s (Unit: second) |
| 12. IE_Imi=-100m | \rightarrow Minimum current range = -100mA (Unit: A) |
| 13. IE_Ima=100m | \rightarrow Maximum current range = 100mA (Unit: A) |
| 14. IE_WZmax=10 | → Delay = 10s |
| 15. IE_Srate=10m | \rightarrow Scan rate = 10mV/s (Unit: V/s) |

The command *IE* will run the IE measurement and the data will be saved in Zahner binary file and the text file.

The command *CHECKIE* makes sure that all the parameters are in the range of the potentiostat.



4.5.3 Cyclic voltammetry (CV)

In the command strings provided below, each parameter required for CV measurement is assigned a value and then a CV is measured. Here also the use of the rule file is disabled (*UseRuleFile=0*).

1:CV_Pstart=0:CV_Pupper=1:CV_Plower=-1:CV_Pend=0:

1:CV_Tstart=10:CV_Tend=20:

1:CV_Srate=100m:CV_Periods=2:CV_PpPer=500:

1:CV_Imi=-100m:CV_Ima=100m:

1:CV_AutoReStart=-1:CV_AutoScale=-1:

1:CHECKCV:

1:CV:

Here,

| 1. | CV_Pstart=0 | \rightarrow Start potential (E start = 0 V) |
|----|---------------|---|
| 2. | CV_Pupper=1 | \rightarrow Upper potential (E upper = 1 V) |
| 3. | CV_Plower=-1 | \rightarrow Lower potential (E lower = -1 V) |
| 4. | CV_Pend=0 | \rightarrow End potential (E end = 0 V) |
| 5. | CV_Tstart=10 | \rightarrow Time before starting CV (start time = 10 s) |
| 6. | CV_Tend=20 | \rightarrow Time after ending CV (hold time = 20 s) |
| 7. | CV_Srate=100m | → Slew rate = 100 mV/s (unit: V/s) |
| 8. | CV_Periods=2 | \rightarrow CV periods = 2 (# of cylces) |





- 9. $CV_PpPer=500$ \rightarrow Points per periods = 500 (samples/cycles)
- 10. CV_Imi=-100m → Minimum current = -100mA (unit: A) cathodic current range
- 11. CV_Ima=100m → Maximum current = 100mA (unit: A) anodic current range
- 12. CV_AutoReStart=-1 \rightarrow Overflow restart (-1=on, 0=off)
- 13. CV_AutoScale=-1 \rightarrow Underflow restart (-1=on, 0=off)

The command *CHECKCV* checks if all the values are correct and in the range of the potentiostat. It makes sure that the slew rate and points per period do not exceed range. If the values exceed the potentiostat's range then *CHECKCV* results in an ERROR and suggests the new value within the potentiostat's range. The command *CV* will run the CV measurement and the data will be saved in Zahner binary file and the text file.

For ZENNIUM potentiostat → CV_Srate * CV_PpPer / CV_span ≤ 2000 with CV_span = CV_Pupper - CV_Plower Here: CV_span = CV_Pupper - CV_Plower = 1 - (-1) = 2 [V] CV_Srate = 100m [V/s] CV_PpPer = 500 [Samples] Maximum CV_PpPer = 2000 / 100m * 2 = 40000 [Samples]



4.5.4 Remote Sequencer

The Thales Sequencer software can also be used via Thales Remote. For this, the user must write sequences before using Thales Remote. The <u>Zahner Sequencer</u> manual explains the method of writing a sequence.

The sequences must be saved with the name "SequenceXX" (XX= 00, 01, 02 to 09) in the folder c:\thales\script\sequencer\sequences.

Once the required sequences are saved, the user can use the following code in the Remote VI application for using the Thales Sequencer.

1:SELSEQ=04: \rightarrow Select "Sequence04" and load included settings

1:DOSEQ: \rightarrow Run selected sequence

The *SELSEQ=04* asks the Thales Remote to open the sequence04 file in Thales Sequencer and *DOSEQ* starts the sequence measurement.

4.5.4.1 Set Sequencer Parameters

Sequencer Parameters can be defined in the "sequence##.seq" file. For this refer to the <u>sequencer manual</u>.

Single parameters can be set by remote commands. The measurement parameters can be defined either by loading sequences (SELSEQ=) or by setting them manually.

Setting parameters and selecting sequences will overwrite the parameter values. Only the last setting is valid.

- 1:SEQ_EUPPER= \rightarrow upper potential limit [V]
- 1:SEQ_ELOWER= \rightarrow lower potential limit [V]
- 1:SEQ_POTOFLO= → potential latency window setting =-1 do not turn off
 - =0 turn off immediately
 - =+t turn off after t seconds beyond limits
- 1:SEQ_IUPPER= \rightarrow upper current limit [A]
- 1:SEQ_ILOWER= \rightarrow lower current limit [A]

| ZAHNER | Thales Remote-2 | | | | |
|----------------|--|--|--|--|--|
| 1:SEQ_CUROFLO= | → current latency window setting =-1 do not turn off =0 turn off immediately =+t turn off after t seconds beyond limits | | | | |
| 1:SEQ_IRANGE= | \rightarrow current range [A] (for pot. sequencer commands) | | | | |
| 1:SEQ_RODROP= | ohmic drop [Ω] for iR-drop compensation =0 disable iR-drop compensation =+r ohmic value | | | | |

After each sequencer measurement the SEQ_RODROP value is reset to "0" and iRdrop compensation is deactivated. So this value has to be defined before each sequencer measurement with iR-drop compensation.

| 1:SEQ_ACQ=channel;select; | ightarrow select acquisition channels for sequencer | | | | | |
|---------------------------|---|--|--|--|--|--|
| | <i>channel</i> = number of ACQ channel | | | | | |
| | select = 0 disable ACQ channel for SEQ | | | | | |
| | 1 enable ACQ channel for SEQ | | | | | |

The available ACQ channels for sequencer can be read by SENDSEQACQSETUP. Sequencer can record up to 8 additional ACQ channels. ACQ channels have to be acquired in the Thales software ACQ. All channels (maximum up to 8) marked as "display channels" are available for the sequencer software. Please refer to <u>signal</u> acquisition manual for details.

1:SEQ_ACQENA=

- \rightarrow ACQ recording of selected channels
 - = 0 (disable ACQ recording in Sequencer)
 - = 1 (enable ACQ recording in Sequencer)



4.6 File handling

The file name, folder destination, and the file saving format (explained in section 2.4) can also be defined using the command strings in the Thales Remote software. The strings provided below handle the file name, folder path, and the saving format. The allowed characters are listed in section 2.4.

1:AAA_PATH=c:\thales\temp: \rightarrow Save measured files in folder c:\thales\temp

- 1:AAA_ROOT=test: \rightarrow File name=test
- 1:AAA_MOD=1: → Saving mode

(0=date and time, 1=incremental count, 2=individual)

1:AAA_NUM=0: \rightarrow Count number (for AAA_MOD=1)

Here, AAA can be replaced for EIS, IE, CV, and SEQ to define the file name, folder path, and saving format for EIS, IE, CV, and SEQ measurement.

4.7 Export ASCII Data Settings

With the command *EIS*, an EIS measurement will be carried out and the data will be exported to a predefined folder. The measured spectrum will be saved in both Zahner binary (.ism) and ASCII format (.txt).

The output format of the ASCII data corresponds to the display format in the Thales SIM program. To change the data of the ASCII export, the standard display format of ism files in SIM must be adapted.

To do this, an EIS spectrum must be loaded in SIM. Then the display format can be set accordingly (refer to <u>SIM manual</u> chapter 3.2). To save these settings as the new standard settings refer to <u>SIM manual</u> chapter 8 and ensure to leave the setup name empty (only confirm with ENTER) to save the settings as the default.



Choose between different data sets

| plot linetype | | | | |
|---------------|--|--|--|--|
| pixel | | | | |
| line | | | | |
| smooth | | | | |
| nome 🗌 | | | | |

The plot linetype will choose the type of data points:

- select "pixel" or "line" to export measured data points
- select "smooth" to export smoothed data points (with a frequency resolution defined in the SIM setup)
- select "pixel" AND "smooth" to export measured data points followed by a smoothed data table



4.8 Remote – FRA-Mode

The Thales FRA mode can also be used in the Thales Remote software. For measurements with the FRA probe, suitable voltage and current gains must be provided for the external power supply or load in question. These gains and the current/voltage limits can be set using the tokens listed below. In addition, offset deviations can be adjusted individually for the input and output variables in the current/voltage channels. The command strings define the FRA-related parameters.

| 1.EDA_1. | \rightarrow Sot EDA mode 0-off 1-on |
|----------|---------------------------------------|
| I.FKA=I. | \rightarrow Set FRA mode 0=01, 1=01 |

- 1:FRA_POT_IN=: → Gain-Factor FRA voltage-in
- 1:FRA_POT_OUT=: → Gain-Factor FRA voltage-out
- 1:FRA_POT_MIN=: \rightarrow FRA minimum voltage (unit: V)
- 1:FRA_POT_MAX=: \rightarrow FRA maximum voltage (unit: V)
- 1:FRA_CUR_IN=: → Gain-Factor FRA current-in
- 1:FRA_CUR_OUT=: → Gain-Factor FRA current-out
- 1:FRA_CUR_MIN=: → minimum current (unit: A)
- 1:FRA_CUR_MAX=: \rightarrow maximum current (unit: A)
- 1:FRA_POT_IN_OFF=: \rightarrow Offset FRA voltage-in *)
- 1:FRA_POT_OUT_OFF=: \rightarrow Offset FRA voltage-out *)
- 1:FRA_CUR_IN_OFF=: → Offset FRA current-in *)
- 1:FRA_CUR_OUT_OFF=: \rightarrow Offset FRA current-out *)
- 1:FRAGAL=1: \rightarrow FRA Potentiostat-Mode (0=Pot, 1=Gal)

*) This offset values cannot be changes in EIS-mode (FRA disabled)

The rule file saved for the EIS measurements cannot be used in the EIS measurement using the FRA. Without a rule file, the user can use the commands used for EIS to carryout EIS measurement.

1:Cset=1:Ampl=500:Pot=-1: 1:ScanStrategy=0:ScanDirection=0: 1:Fmin=1:Fstart=1000:Fmax=50000: 1:dfl=4:dfm=8:Nwl=5:Nws=10: 1:EIS:



In FRA mode the set value is always output. The settings for the external device (feedback type, control type, output on/off) must be made separately.

It is not possible to switch off the external device via the FRA interface!

The FRA mode must be permanently set for FRA measurements (FRA=1). You must not switch back to the main potentiostat EIS mode (FRA=0) in the meantime.

The changes to offset values and gains of the output channels only become effective when a new setpoint (Cset=/Pset=) is set.

The changes to offset values and gains of the input channels only become effective when a new data is measured.

| startphase slewrate V/s: | 31.936m |
|----------------------------------|---------|
| break on overload factor: | 2 |
| MIE range delay: | 1 |
| temp. protocol source: | 0 |
| PMUX installed: | 0 |
| FRA voltage-in [V_cell/V_acq]: | 1 |
| FRA voltage-out [V_cell/V_ctrl]: | 1 |
| FRA min.voltage [V_cell]: | -10 |
| FRA max.voltage [V_cell]: | 10 |
| FRA current-in [A_cell/V_acq]: | 2 |
| FRA current-out [A_cell/V_ctrl]: | -2 |
| FRA min.current [A_cell]: | -20 |
| FRA max.current [A_cell]: | 20 |
| FRA voltage-in offset: | -4e-2 |
| FRA voltage-out offset: | 6 |
| FRA current-in offset: | -15.3 |
| FRA current-out offset: | -2.2e-2 |

4.9 Data acquisition / Virtual instruments

The ZENNIUM series potentiostats can be easily used with an external measurement system (i.e., temperature controller or a thermometer) and can incorporate the data from the external device in the EIS, CV, and IE measurements. To acquire the signal from the external device, the Thales "Signal Acquisition" software is used.



In this section, the Eurotherm (NET-VI, Channel:6144) will be used as an example of the external device and will be configured for use in the Thales Remote. First of all, the user must set up the Eurotherm as explained in the application note <u>Eurotherm</u>. Afterward, the user can use the command strings provided below to start the VI software (Eurotherm) and read the signal from channels in the Thales Signal Acquisition software.

| 1:VI_PATH=c:\flink\NetVI: | → VI folder |
|---------------------------|--|
| 1:VI_INI=Eurotherm: | ightarrow Define the name of the EuroTherm.ini file |
| 1:VI_EXE=EuroTherm: | ightarrow Define the name of the EuroTherm.exe file |
| 1:STARTVI: | → Start VI software |
| 1:CHANNEL=0: | \rightarrow Access channel display "0" |
| 1:ANALOGIN: | ightarrow Read analog-channel (defined with CHANNEL) |
| 1:ANALOGALL: | ightarrow Read all analog-channels |

4.10 MIO card

If the user has a MIO card installed in ZENNIUM series potentiostat then the following commands can be used to set the analog/digital output. The user must define the channel to specify the output to that channel.

| 1:CHANNEL=: | \rightarrow Define channel |
|----------------|---|
| 1:ANALOGOUT=: | ightarrow Set analog output of the MIO |
| 1:DIGITALOUT=: | ightarrow Set digital output of MIO |
| 1:DACOUT=: | ightarrow Output function for DAC16/MIC |

4.11 Acquire system parameters

Using remote software, the user can remotely control the Thales software. Here it is of utmost importance that the user can remotely check the system specification and the set values of every parameter in the Thales software. For example, the current/potential range, number of extension possible (DEV%), and potentiostatic/galvanostatic mode, and so on. To get this information the user can use the following commands

| 1:SENDSETUP: | → Send ZENNIUM series potentiostats specifications | | | | | | |
|--------------------|--|--|--|--|--|--|--|
| 1:SENDCVSETUP: | \rightarrow Send CV setup information | | | | | | |
| 1:SENDIESETUP: | \rightarrow Send IE setup information | | | | | | |
| 1:SENDPAD4SETUP: | ightarrow Send PAD4 setup information | | | | | | |
| 1:SENDFRASETUP: | ightarrow Send FRA setup information | | | | | | |
| 1:SENDACQSETUP: | ightarrow Send ACQ setup information | | | | | | |
| 1:SENDSEQACQSETUP: | ightarrow Send SEQUENCER ACQ setup information | | | | | | |

The User can also access the series number of the main potentiostat and the available boosters/extensions.

| 1:ECWNUM: | \rightarrow Provide series number & name (main device) |
|-----------|--|
| 1:DEVNUM: | \rightarrow Provide series number & name (active device) |
| 1:ALLNUM: | ightarrow Provide series numbers & names (all devices) |

Here, ALLNUM will provide the information about the main potentiostat, connected boosters, and the RMux cards.



4.12 Additional commands

4.12.1 PAD4 setup

The user can define the PAD4 setup in Remote VI software. The commands **PAD4**= deals with 3 parameters i) card #, ii) channel #, and iii) status. For example

- 1:PAD4=1;1;1: \rightarrow PAD4 card = 1, channel 1, switch on
- 1:PAD4=2;4;0: \rightarrow PAD4 card = 2, channel 4, switch off
- 1:PAD4ENA=1: → Enable PAD4

The user can switch the type of PAD4 channels between voltage sense (standard configuration) and current sense (with additional shunt resistor).

| 1:PAD4MOD=0: | → Set $\frac{U_{pad4}}{I_{main}}$ | all | PAD4 | channels | to | voltage | mode | $Z_{pad4} =$ |
|--------------|--|-----|------|----------|----|---------|------|--------------|
| 1:PAD4MOD=1: | \rightarrow Set $\frac{U_{main}}{I_{pad4}}$ | all | PAD4 | channels | to | current | mode | $Z_{pad4} =$ |

In voltage mode the input voltage range (standard: 4 V) can be adjusted for userdefined voltage cables or different voltage ranges of the PAD4-LC and PAD4-HZ addon cards. The command **PAD4_PRANGE=** deals with 3 parameters i) card #, ii) channel #, and iii) range. For example

| 1:PAD4_PRANGE=1;1;8: | \rightarrow PAD4 card = 1, channel 1, 8 V input range |
|----------------------|---|
| | |

1:PAD4_PRANGE=2;4;1: → PAD4 card = 2, channel 4, 1 V input range

In current mode the input current range has to be defined corresponding to the used current shunt resistor. The command *PAD4_RSHUNT=* deals with 3 parameters i) card #, ii) channel #, and iii) range. For example

| 1:PAD4_RSHUNT=1;1;10m: | \rightarrow PAD4 card = 1, channel 1, 10mR shunt resistor |
|------------------------|---|
| 1:PAD4_RSHUNT=2;4;40m: | \rightarrow PAD4 card = 2, channel 4, 40mR shunt resistor |

PAD4-LC has a standard input voltage range of $\pm 1 \text{ V}$ (normal PAD4/PAD4-HC have $\pm 4 \text{ V}$). For this a shunt resistor in current mode has to be defined as 4x shunt resistor when using the PAD4-LC addon card type.

For Eample: 1:PAD4_RSHUNT=2;4;40m: → PAD4-LC card = 2, channel 4, 10mR shunt resistor



4.12.2 Potential range

The IM6/ZENNIUM series potentiostats work at different potential ranges. For example, a ZENNIUM PRO can be set for the measurements up to ± 5 V or ± 15 V. Using the command provided below the user can select the low potential or high potential range setting.

1:Potrange=X:

 \rightarrow Potential range: 0 = low potential range

1 = high potential range

4.12.3 Shunt range

In the IM6/ZENNIUM series potentiostats, the user can also specify the minimum and maximum shunt resistance(s) for the measurement.

1:Rmin=X → Minimum shunt resistance index

1:Rmax=X \rightarrow Maximum shunt resistance index

4.12.4 Clear memory

The IM6/ZENNIUM series potentiostats use internal memory during the measurements and once the measurement is done then save the measurement data at the computer hard disk. However, for a very long measurement (i.e., CV measurement with a very low slew rate) the available memory may not be enough. Here, with the commands below user can clean the potentiostats memory from the last measurement and increase the available memory for the measurement.

- 1:CLRACQ: \rightarrow Clear acquisition memory
- 1:CLREIS: \rightarrow Clear EIS measurement from SIM memory
- 1:CLRCV: \rightarrow Clear CV measurement from SIM memory
- 1:CLRIE: \rightarrow Clear IE measurement from SIM memory



5 Commands

In this chapter, different commands for electrochemical measurements are provided.

| SENDSETUP | request potentiostat (IM6/ZENNIUM) for setup |
|-----------------|---|
| CURRENT | measure current |
| POTENTIAL | measure potential |
| IMPEDANCE | measure impedance |
| PAD4IMP | measure parallel impedances at main and PAD4 channels |
| EIS | measure, save and export EIS spectrum |
| CV | measure, save and export CV spectrum |
| IE | measure, save and export IE spectrum |
| DOSEQ | measure a sequence (Sequencer) |
| CURFAST | measure current fast |
| POTFAST | measure potential fast |
| ANALOGIN | read ANALOG-Channel (ANALOGCHANN) |
| ANALOGALL | read all active ACQ-Channels |
| DIGITALIN | read DIGITAL-Channel (DIGITALCHANN) |
| CALOFFSETS | offset calibration |
| ALLNUM | print all devices & relay number |
| ECWNUM | print series number of main device |
| DEVNUM | print series number of controlled potentiostat |
| STARTVI | start virtual instrument (VI) |
| SENDACQSETUP | request ACQ settings |
| CLRACQ | delete old ACQ-Data |
| CLRCV | delete old CV-Data |
| CLREIS | delete old EIS-Data |
| CLRIE | delete old IE-Data |
| CLRPOL | delete old POL-Data |
| CLRSIM | delete old SIM-Data |
| CHECKCV | check CV-Parameters |
| CHECKIE | check IE-Parameter |
| SENDCVSETUP | request CV-settings |
| SENDIESETUP | request IE-settings |
| SENDPAD4SETUP | request PAD4-settings |
| SENDFRASETUP | request FRA-settings |
| CHECKEIS | request EIS-settings |
| SENDSEQACQSETUP | request SEQUENCER ACQ settings |
| DEVINF | print type and serial no of selected external potentiostat |
| SETUSB | switch selected PP2x2/XPot2/EL1002 to SCPI interface mode with turning off the device |



| HOT2USB | switch selected PP2x2/XPot2/EL1002 to SCPI interface mode without turning off the device |
|------------------|---|
| DEV%= | choose controlled device (PP/EL/R-Mux) |
| DEVHOT%= | <pre>select PP2x2/XPot2/EL1002 device from SCPI interface mode without turning off the device</pre> |
| Pset= | set potential value (V) |
| Cset= | set current value (A) |
| Frq= | set AC-Frequency (Hz) |
| Ampl= | set AC-Amplitude (mA) |
| Nw= | set Number of averages |
| Pot= | turn potentiostat OFF/ON (Pot=0/-1 resp.) |
| Gal= | choose potentiostatic/galvanostatic and |
| GAL= | pseudo-galvanostatic mode |
| GlobalAck= | <pre>global acknowledge (0=off,1=ON,2=ON/error info)</pre> |
| UseRuleFile= | use rule file $(1 = YES, 0 = NO)$ |
| Fmin= | lower AC frequency limit (Hz) |
| Fstart= | starting frequency (Hz) |
| Fmax= | upper AC frequency limit (Hz) |
| dfm= | steps per decade Frq >66Hz |
| dfl= | steps per decade Frq<=66Hz |
| Nwl= | averages for Frq <= 66Hz |
| Nws= | averages for Frq > 66Hz |
| ScanStrategy= | 0=single sine, 1=multi sine,2=frequency table |
| ScanDirection= | 0=from Fstart to Fmax, 1=from Fstart to Fmin |
| Rmin= | lower shunt resistance index |
| Rmax= | higher shunt resistance index |
| Potrange= | input potential range index |
| Imi= | minimum current limit |
| Ima= | maximum current limit |
| SELSEQ= | select sequence 00 \rightarrow 09 (Sequencer) |
| FRA= | set FRA mode 0=off, 1=FRA mode |
| FRA_POT_IN= | Gain-Factor FRA Potential IN |
| FRA_POT_OUT= | Gain-Factor FRA Potential OUT |
| FRA_POT_MIN= | minimum potential (V) |
| FRA_POT_MAX= | maximum potential (V) |
| FRA_CUR_IN= | Gain-Factor FRA Current IN |
| FRA_CUR_OUT= | Gain-Factor FRA Current OUT |
| FRA_CUR_MIN= | minimum current (A) |
| FRA_CUR_MAX= | maximum current (A) |
| FRA_POT_IN_OFF= | Offset FRA Potential IN |
| FRA_POT_OUT_OFF= | Offset FRA Potential OUT |
| FRA_CUR_IN_OFF= | Offset FRA Current IN |



| FRA_CUR_OUT_OFF= | Offset FRA Current Out |
|------------------|--|
| FRAGAL= | FRA Potentiostat-Mode 0=Pot, 1=Gal |
| CV_Pstart= | CV starting potential (V) |
| CV_Tstart= | CV starting hold time (s) |
| CV_Pupper= | CV upper (reversing) potential (V) |
| CV_Plower= | CV lower (reversing) potential (V) |
| CV_Pend= | CV ending potential (V) |
| CV_Tend= | CV ending hold time (s) |
| CV_Srate= | CV slew rate (V/s) |
| CV_Periods= | CV count of periods (number of cycles) |
| CV_PpPer= | CV points per period (samples per cycles) |
| CV_Imi= | CV minimum current (A) |
| CV_Ima= | CV maximum current (A) |
| CV_Odrop= | CV Ohmic drop (Ω) |
| CV_Sstart= | CV recording start time (s) |
| CV_Send= | CV recording end time (s) |
| CV_AutoReStart= | CV auto rescale at current overflow (0/-1) |
| CV_AutoScale= | CV auto rescale at current underflow $(0/-1)$ |
| CV_AFGena= | CV enable optional Analog Function Generator $(0/1)$ |
| PAD4ENA= | PAD4 enable PAD4 recording (0/1) |
| PAD4= | activate PAD4 channel e.g. PAD4=1;1;1 PAD1,Chan1,ON |
| PAD4MOD= | PAD4 mode potential/current (0/1) |
| IE_EckPot1= | IE first edge potential (V) |
| IE_EckPot2= | IE second edge potential (V) |
| IE_EckPot3= | IE third edge potential (V) |
| IE_EckPot4= | IE forth edge potential (V) |
| IE_EckPot1rel= | IE first edge potential 0=abs,-1=rel |
| IE_EckPot2rel= | IE second edge potential 0=abs,-1=rel |
| IE_EckPot3rel= | IE third edge potential 0=abs,-1=rel |
| IE_EckPot4rel= | IE forth edge potential 0=abs,-1=rel |
| IE_Resolution= | IE potential resolution (V) |
| IE_WZmin= | IE minimum waiting time (WZ=Wartezeit) (s) |
| IE_WZmax= | IE maximum waiting time (s) |
| IE_Torel= | IE relative current tolerance dI in % |
| IE_Toabs= | IE absolute current tolerance dI in A |
| IE_Odrop= | IE Ohmic drop (Ω) |
| IE_SweepMode= | IE sweep mode 0=steady state,1=fixed sampling,2=dynamic scan |
| IE_Srate= | IE linear scan slew rate (V) |
| IE_Imi= | IE minimum current (A) |
| IE_Ima= | IE maximum current (A) |
| PAD4_PRANGE= | PAD4 voltage range e.g. PAD4_PRANGE=1;1;8 PAD1,Chan1,8V |



| PAD4_RSHUNT= | PAD4 voltage range e.g. PAD4_RSHUNT=1;2;10m PAD1,Chan2,10mR |
|--------------|--|
| AVERAGES= | count of averages (1005000) for potfast/curfast |
| CHANNEL= | I/O for ACQ-access (read analog, set digi,) |
| ANALOGOUT= | give value at ACQCHANN out |
| DIGITALOUT= | writes 015 to digital output of MIO |
| DACOUT= | separate Output function for DAC16/MIO |
| | solved problem with IN-OUT channel, same card |
| SEQ_RODROP= | ohmic drop value for IR-drop compensation in SEQUENCER (will be reset to 0° after performing a sequencer measurement) |
| SEQ_ACQ= | <pre>select ACQ channel e.g. =1;1 ACQ,Chan1,ON for SEQUENCER</pre> |
| SEQ_ACQENA= | activate ACQ channles in SEQUENCER (only selected channels) |
| SEQ_MAXTIME= | set maximum runtime [h] for SEQUENCER (0.11000) |
| SEQ_EUPPER= | set upper potential limit [V] for SEQUENCER |
| SEQ_ELOWER= | set lower potential limit [V] for SEQUENCER |
| SEQ_IUPPER= | set upper current limit [A] for SEQUENCER |
| SEQ_ILOWER= | set lower current limit [A] for SEQUENCER |
| SEQ_IRANGE= | set current range [A] for SEQUENCER |
| SEQ_POTOFLO= | set potential latency window (POT-OFF) |
| | =-1 -> do not turn off |
| | = t -> POT-OFF after "t" seconds in limitation |
| | = 0 -> turn off immediately |
| SEQ_CUROFLO= | set current latency window (CUR-OFF) |
| | =-1 -> do not turn off |
| | = t -> CUR-OFF after "t" seconds in limitation |
| | = 0 -> turn off immediately |
| EIS_MOD= | EIS file mode (0=date&time,1=counter,2=individual) |
| EIS_NUM= | EIS file counter (mode=1) |
| CV_MOD= | CV file mode (0=date&time,1=counter,2=individual) |
| CV_NUM= | CV file counter (mode=1) |
| IE_MOD= | IE file mode (0=date&time,1=counter,2=individual) |
| IE_NUM= | IE file counter (mode=1) |
| SEQ_MOD= | SEQ file mode (0=date&time,1=counter,2=individual) |
| SEQ_NUM= | rem SEQ file counter (mode=1) |
| EIS_PATH= | set EIS data path |
| CV_PATH= | set CV data path |
| IE_PATH= | set IE data path |
| SEQ_PATH= | set SEQ data path |
| VI_PATH= | set VI rtm path |
| EIS_ROOT= | set EIS file rootname (mode0,1) |
| CV_ROOT= | <pre>set CV file rootname (mode0,1)</pre> |
| IE_ROOT= | set IE EIS file rootname (mode0,1) |



SEQ_ROOT= set SEQ file rootname (mode0,1)
VI_INI= call c:\thales\netvi\vi.exe VI-INI-file
VI_EXE= name of the VI

5.1 New commands

Many tokens/commands are "RESERVED", which are left for later development or user-defined functions. Each command/token must be 20 characters long and if a token is smaller than 20 characters, the rest must be filled with "blank" characters. A list of reserved tokens for future use is provided in the folder C:\Thales\script\ remote2\manuals. Further information about the reserved

For user-defined functions, the user must also add a proof-read routine to make sure that the parameter is within the range of the potentiostat/or the defined range.



6 Errors - Table

In this chapter, an error list is provided. This list should help the users in swiftly preparing an error-free remote script. To get these error messages the Global Acknowledge must be set to 2. The same list is also provided in the folder c:\thales\script\remote2\manuals\error.xlsx.

| Cod e | Meaning | Reason | Status | Tip |
|----------|--------------------------------|--------|--------|-----------------|
| 0 | OK | | | |
| 1 | ERROR_TOO_MANY_FILES | | | |
| 2 | ERROR_FILE_ALREADY_OPEN | | | |
| 3 | ERROR_FILE_NOT_OPEN | | | |
| 4 | ERROR_FILE_NOT_FOUND | | | |
| 5 | ERROR_LOAD_ERROR | | | |
| 6 | ERROR_VERIFY_ERROR | | | |
| 7 | ERROR_DEVICE_NOT_PRESENT | | | |
| 8 | ERROR_NO_INPUT_FILE | | | |
| 9 | ERROR_NO_OUTPUT_FILE | | | |
| 10 | ERROR_NEXT_WITHOUT_FOR | | | |
| 11 | ERROR_SYNTAX_ERROR | | | |
| 12 | ERROR_RETURN_WITHOUT_GOS UB | | | |
| 13 | ERROR_OUT_OF_DATA | | | POT still ON |
| 14 | ERROR_ILLEGAL_QUANITITY | | | |
| 15 | | | | |
| 16 | | | | |
| 17 | | | | |
| 18 | | | | |
| 19 | | | | |
| 20 | | | | |
| 21 | | | | |



| | | 1 | |
|----|-------------------------------|---|--|
| 22 | | | |
| 23 | | | |
| 24 | | | |
| 25 | | | |
| 26 | | | |
| 27 | | | |
| 28 | | | |
| 29 | | | |
| 30 | | | |
| 31 | | | |
| 32 | ERROR_LINE_NUMBER_TOO_BI G | | |
| 33 | | | |
| 34 | | | |
| 35 | | | |
| 36 | | | |
| 37 | | | |
| 38 | | | |
| 39 | | | |
| 40 | | | |
| 41 | | | |
| 42 | ERROR_UNDEFINED | | |
| 43 | | | |
| 44 | | | |
| 45 | | | |
| 46 | | | |
| 47 | | | |
| 48 | | | |
| 49 | | | |
| 50 | | | |



| 51 | | | | |
|----|--|-----------------------------|---|--|
| 52 | | | | |
| 53 | | | | |
| 54 | | | | |
| 55 | | | | |
| 56 | | | | |
| 57 | | | | |
| 58 | | | | |
| 59 | | | | |
| 60 | | | | |
| 61 | | | | |
| 62 | | | | |
| 63 | | | | |
| 64 | | | | |
| 65 | ERROR_USER_INTERRUPT | HOME/ESCAPE | 0 | |
| 67 | ERROR_IMPEDANCE_DISABLED | NO AC DEFINED or POT OFF | 0 | |
| 68 | ERROR_POTENTIOSTATIC_ LOOP_NOT_STABLE | | 0 | |
| 69 | ERROR_POTENTIOSTATIC_ LOOP_ INTERRUPTED | | 0 | |
| 70 | ERROR_CURRENT_NOT_STEADY | | 0 | |
| 71 | ERROR_CURRENT_LIMITS_EXC EEDED | | 0 | |
| 72 | ERROR_POTENTIOSTAT_IS_OF F | | 0 | |
| 73 | ERROR_POTENTIAL_LIMITS_E XCEEDED | | 0 | |
| 74 | ERROR_NOT_ENOUGH_MEMORY | | 0 | |
| 75 | ERROR_IMPROPER_DATA_FROM _NOISE_PROBE | | 0 | |
| 76 | ERROR_NO_PROPER_TEXT_FIL E | | 0 | |



| 77 | ERROR_MEASUREMENT_INTERR UPTED_BY_NMI | | 0 | |
|-----|--|--------------------------------|---|--|
| 78 | ERROR_MEASUREMENT_STOPPE D_POT_STILL_ON | | 0 | |
| 79 | | | | |
| 80 | | | | |
| 81 | | | | |
| 82 | | | | |
| 83 | | | | |
| 84 | | | | |
| 85 | | | | |
| 86 | | | | |
| 87 | | | | |
| 88 | | | | |
| 89 | | | | |
| 90 | | | | |
| 91 | | | | |
| 92 | | | | |
| 93 | | | | |
| 94 | | | | |
| 95 | | | | |
| 96 | ERROR_OUTA_CHANNEL_NOT_R EGISTERED | | 0 | |
| 97 | ERROR_ACQ_DISPLAY_NOT_RE GISTERED | | 0 | |
| 98 | | | | |
| 99 | ERROR_NO_PAD4_INSTALLED | There is no PAD4 card present. | | |
| 100 | ERROR_PARAMETER_OUT_OF_R ANGE | Sent value too low/high | Val <mi =-1 Val>MA =1</mi | |
| 101 | ERROR_PARAMETER_NOT_INTE GER | Sent value not integer | 2 | |



| 102 | ERROR_ILLEGAL_COMMAND | Illegal command token | 0 | |
|-----|--|--|--------------|---|
| 103 | ERROR_ILLEGAL_COMMAND_DE LIMITER | Wrong format of command token | 0 | |
| 104 | ERROR_PARAMETER_ERROR_IN _MULTICMD | | | |
| 105 | | | | |
| 106 | ERROR ILLEGAL ADRESS | | | |
| 107 | | | | |
| 108 | | | | |
| 109 | | | | |
| 110 | ERROR_CV_REVERSING_POTEN TIALS | Pupper<=Plower | 0 | Pupper<=Plo wer |
| 111 | ERROR_CV_STARTING_POTENT IAL_TOO_HIGH | Pstart>Plower | 0 | Pstart>Plow er |
| 112 | ERROR_CV_POINTS_PER_CYCL E_TOO_HIGH | Maximum points in Status | Max value | Maximum points in Status |
| 113 | ERROR_CV_CYCLE_COUNT_TOO _HIGH | Maximum number of cycles in Status | Max value | Maximum number of cycles in Status |
| 114 | ERROR_CV_AFG_NOT_INSTALL ED | Analog function generator is not available | | |
| 115 | ERROR_NO_SCPI_DEVICE | Can't set device to USB mode | | |
| 116 | ERROR_NO_SCPI_DEVICE | Can't hotswap device (no SCPI device) | | |
| 117 | ERROR_NOT_VALID_IN_FRA | Command is not supported in FRA- Mode | | |
| 118 | ERROR_NOT_VALID_IN_EIS | Command is not supported in EIS- Mode | | |
| 119 | | | | |
| 120 | ERROR_IE_RESOLUTION_TOO_ LOW | Minimum resolution in µV in status | Min value | Minimum resolution in µV in status |



Thales Remote-2

| 121 | ERROR_IE_IMI_IMA | Check IE Imi, Ima values | |
|-----|---|-----------------------------|---|
| 122 | | | |
| 123 | | | |
| 124 | | | |
| 125 | | | |
| 126 | | | |
| 127 | | | |
| 128 | | | |
| 129 | ERROR_SEQ_01_NOT_YET_DEF INED | SEQ ERR1 | 0 |
| 130 | ERROR_SEQ_02_NOT_EXECUTA BLE_RAMP | SEQ ERR2 | 0 |
| 131 | ERROR_SEQ_03_TOO_MANY_LO OPS | SEQ ERR3 | 0 |
| 132 | ERROR_SEQ_04_LOOP_END_BE FORE_START | SEQ ERR4 | 0 |
| 133 | ERROR_SEQ_05_LOOP_WITHOU T_END | SEQ ERR5 | 0 |
| 134 | ERROR_SEQ_06_KERNEL_ERRO R | SEQ ERR6 | 0 |
| 135 | ERROR_SEQ_07_PARAMETER_E RROR | SEQ ERR7 | 0 |
| 136 | ERROR_SEQ_08_TOKEN_DEFIN ITION | SEQ ERR8 | 0 |
| 137 | ERROR_SEQ_09_SEQUENCE_NO T_FOUND | SEQ ERR9 | 0 |
| 138 | ERROR_SEQ_10_CURRENT_OUT _OF_RANGE | SEQ ERR10 | 0 |
| 139 | ERROR_SEQ_11_POTENTIAL_O UT_OF_RANGE | SEQ ERR11 | 0 |
| 140 | ERROR_SEQ_12_SLOPE_EQUAL _ZERO | SEQ ERR12 | 0 |
| 141 | ERROR_SEQ_13_END_AND_STA RT_EQUAL | SEQ ERR13 | 0 |
| 142 | ERROR_SEQ_14_BRACKET_ERR OR | SEQ ERR14 | 0 |



| 143 | ERROR_SEQ_15_ASCII_ERROR | SEQ ERR15 | 0 |
|-----|--|-----------|---|
| 144 | ERROR_SEQ_16_DOUBLE_COMM A | SEQ ERR16 | 0 |
| 145 | ERROR_SEQ_17_NO_REGULAR_ EXPRESSION | SEQ ERR17 | 0 |
| 146 | ERROR_SEQ_18_TOO_MANY_PA RAMETER | SEQ ERR18 | 0 |
| 147 | ERROR_SEQ_19_NOT_YET_DEF INED | SEQ ERR19 | 0 |
| 148 | ERROR_SEQ_20_NOT_YET_DEF INED | SEQ ERR20 | 0 |
| 149 | ERROR_SEQ_21_NOT_YET_DEF INED | SEQ ERR21 | 0 |
| 150 | ERROR_SEQ_22_USAGE_OF_VA RIABLE_CUR | SEQ ERR22 | 0 |
| 151 | ERROR_SEQ_23_USAGE_OF_VA RIABLE_POT | SEQ ERR23 | 0 |
| 152 | ERROR_SEQ_24_USAGE_OF_VA RIABLE_TIM | SEQ ERR24 | 0 |
| 153 | ERROR_SEQ_25_BLOCK_ENDED _NO_START | SEQ ERR25 | 0 |
| 154 | ERROR_SEQ_26_BLOCK_START ED_NO_END | SEQ ERR26 | 0 |
| 155 | ERROR_SEQ_27_NOT_YET_DEF INED | SEQ ERR27 | 0 |
| 156 | ERROR_SEQ_28_NOT_YET_DEF INED | SEQ ERR28 | 0 |
| 157 | ERROR_SEQ_29_NOT_YET_DEF INED | SEQ ERR29 | 0 |
| 158 | ERROR_SEQ_30_NOT_YET_DEF INED | SEQ ERR30 | 0 |
| 159 | ERROR_SEQ_31_NOT_YET_DEF INED | SEQ ERR31 | 0 |
| 160 | ERROR_SEQ_32_NOT_YET_DEF INED | SEQ ERR32 | 0 |
| 161 | | | |
| 162 | | | |
| 163 | | | |